

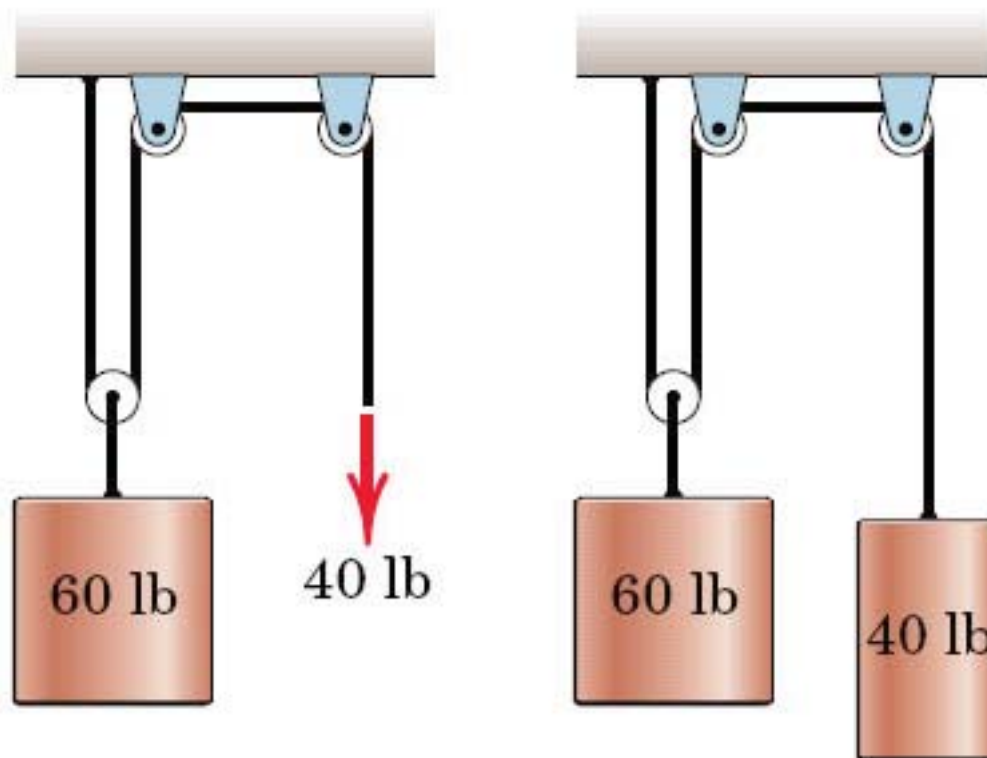
# Equations of Motion

## **Lecture 19**

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**ME 231: Dynamics**

## Question of the Day



Determine the vertical ***acceleration*** of the ***60-lb*** cylinder for each of the two cases.

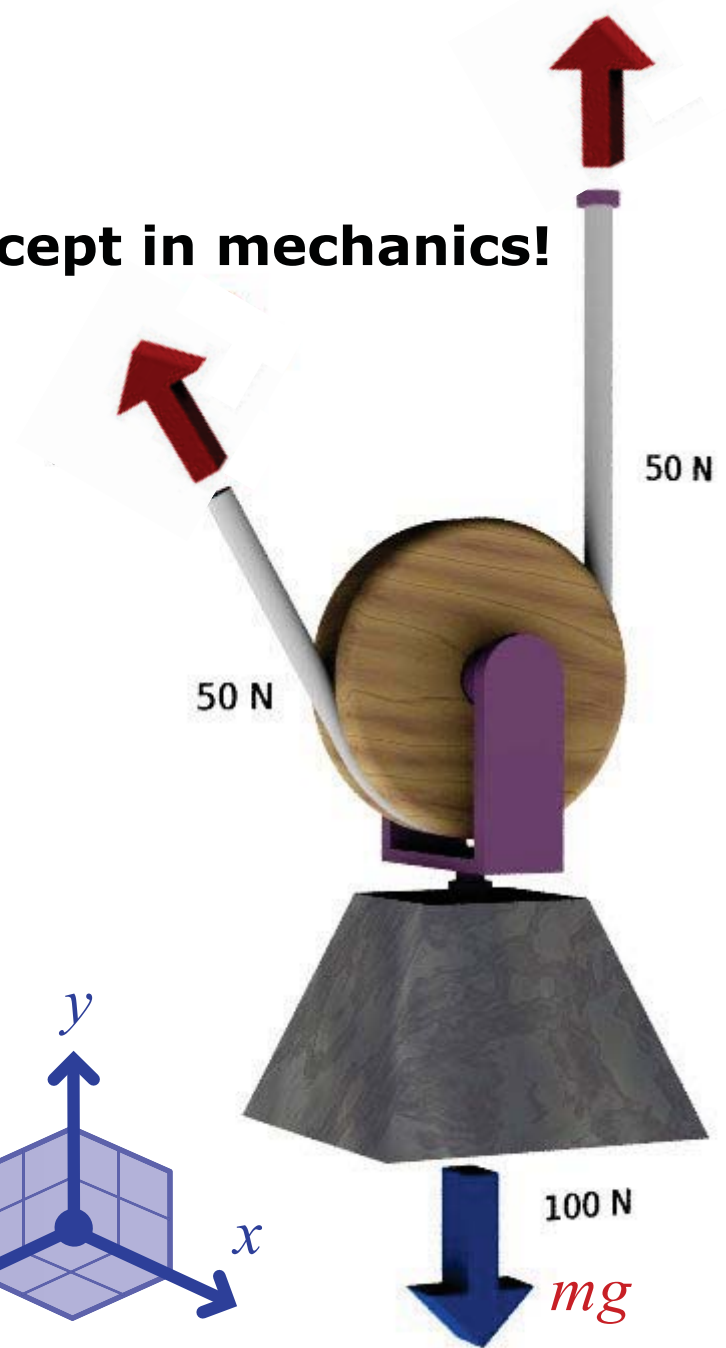
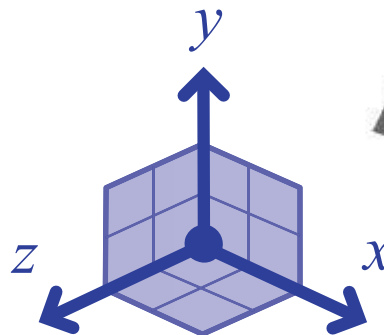
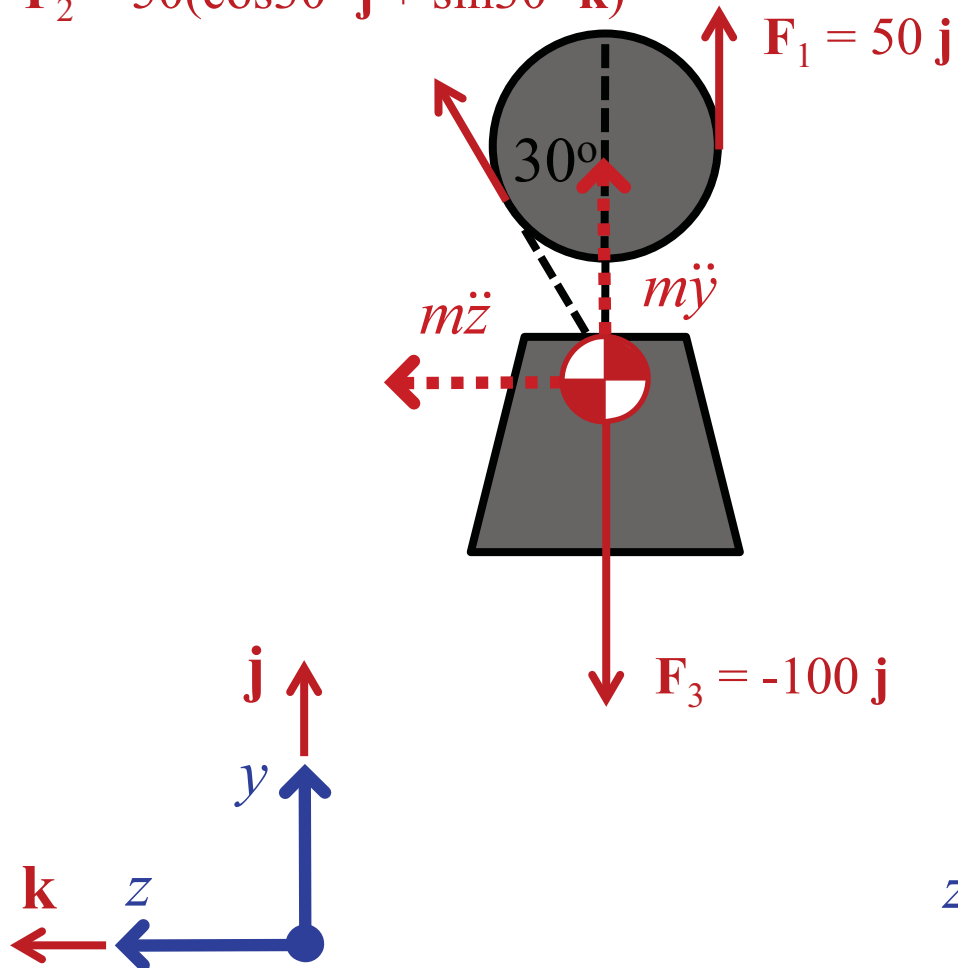
## Outline for Today

- Question of the day
- Free body diagram
- Equations of motion
- Two types of problems
  - Inverse dynamics
  - Forward dynamics
- Constrained vs. unconstrained motion
- Rectilinear motion
- Answer your questions!

# Free Body Diagram

Perhaps the most important concept in mechanics!

$$\mathbf{F}_2 = 50(\cos 30^\circ \mathbf{j} + \sin 30^\circ \mathbf{k})$$



# Equations of Motion

Perhaps the most important concept in dynamics!

- **Vector form** of force-mass-acceleration equation

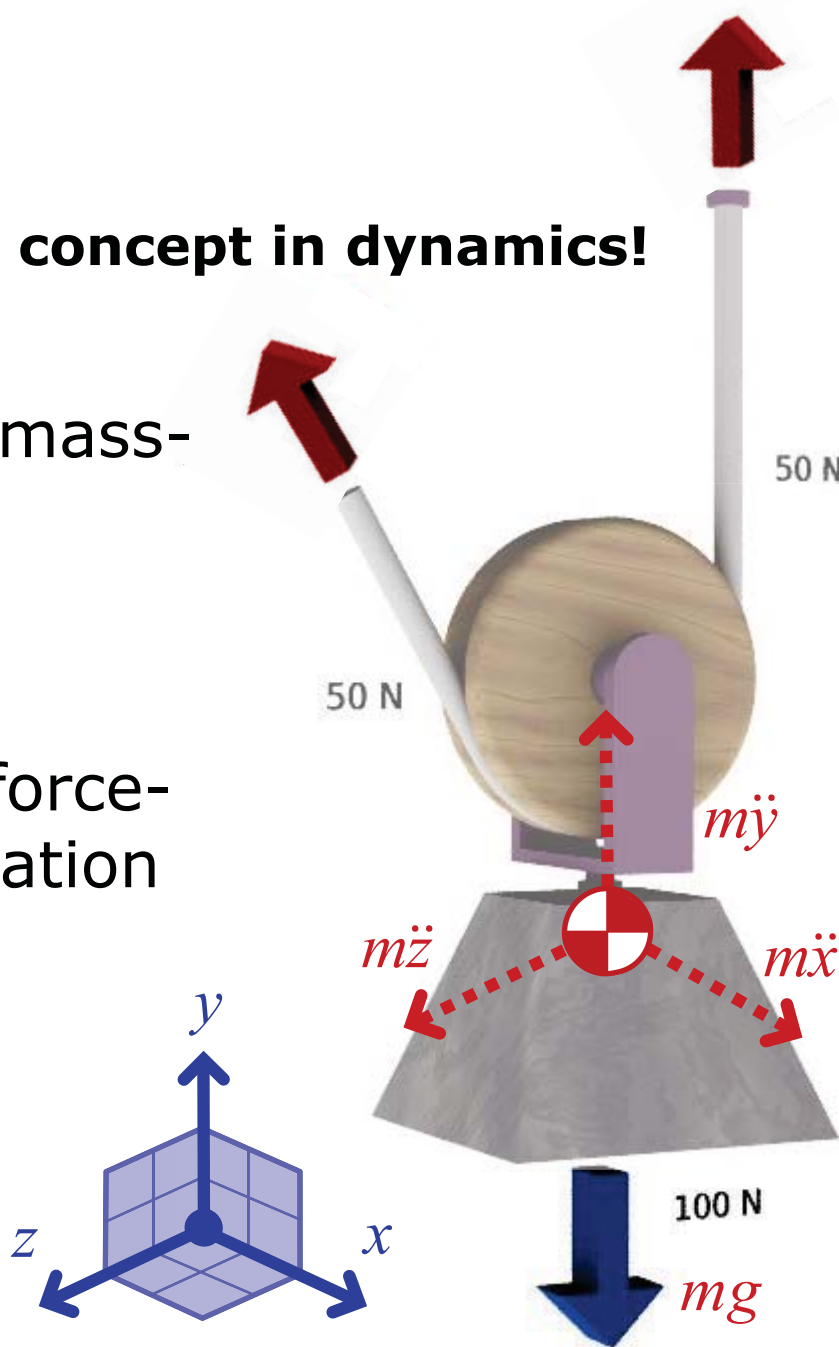
$$\sum \mathbf{F} = m\mathbf{a}$$

- **Component form** of force-mass-acceleration equation

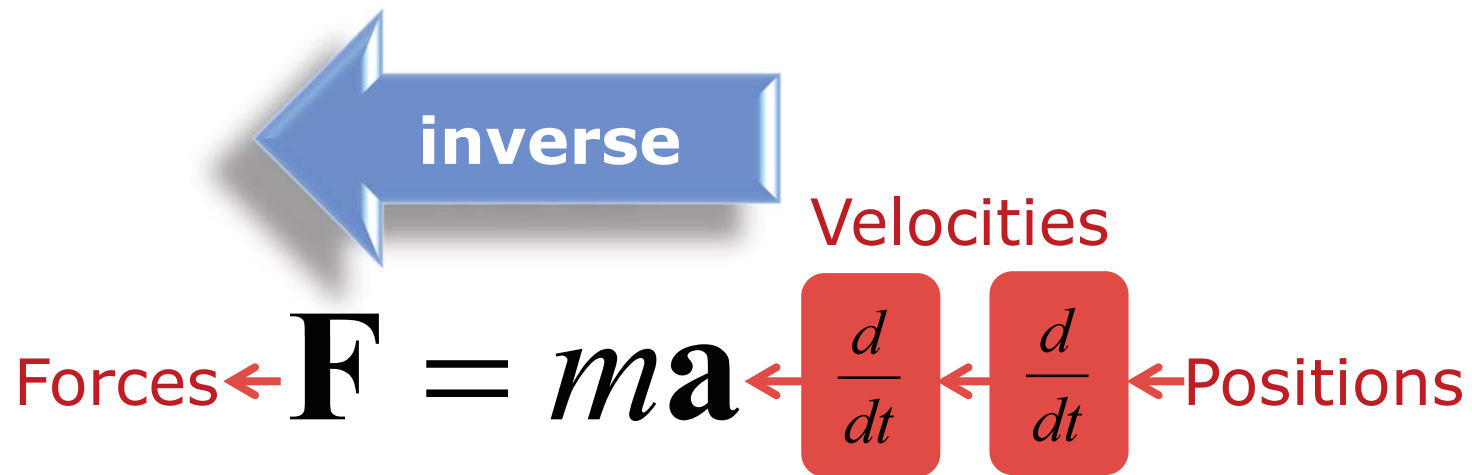
$$\sum F_x = ma_x = m\ddot{x}$$

$$\sum F_y = ma_y = m\ddot{y}$$

$$\sum F_z = ma_z = m\ddot{z}$$

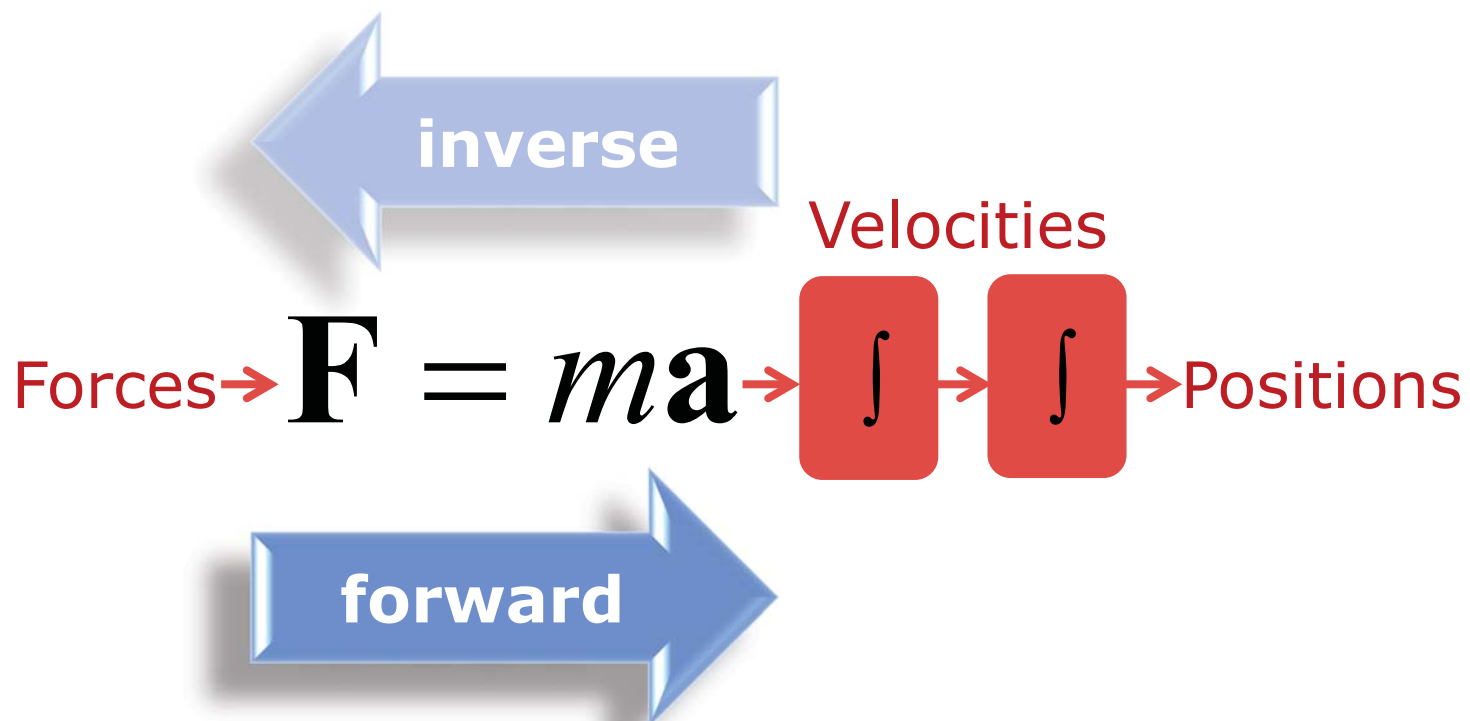


# Inverse Dynamics Problem



- **Accelerations** are specified or determined directly from kinematic conditions
- Determine the corresponding **forces**

## Forward Dynamics Problem



- **Forces** are specified or determined from a FBD
- Determine the corresponding **acceleration**
- If **forces** are functions of **time**, **position**, or **velocity**, then **integrate** differential equation to determine **velocity** and **position**

# Constrained vs. Unconstrained Motion

- Unconstrained
  - **Free** of mechanical guides
  - Follows a **path** determined by its **initial motion** and applied **external forces**
- Constrained
  - Path is partially or totally determined by **restraining guides**
  - All forces (**applied** and **reactive**) must be accounted for in  **$F=ma$**





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# Rectilinear Motion

- **Coordinate** direction (x) **along** the **motion**

$$\sum F_x = ma_x$$

$$\sum F_y = 0$$

$$\sum F_z = 0$$

- **Acceleration**

$$\mathbf{a} = a_x \mathbf{i} + a_y \mathbf{j} + a_z \mathbf{k}$$

$$|\mathbf{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2}$$

- **Coordinate** direction **NOT** **along** the **motion**

$$\sum F_x = ma_x$$

$$\sum F_y = ma_y$$

$$\sum F_z = ma_z$$

- **Resultant force**

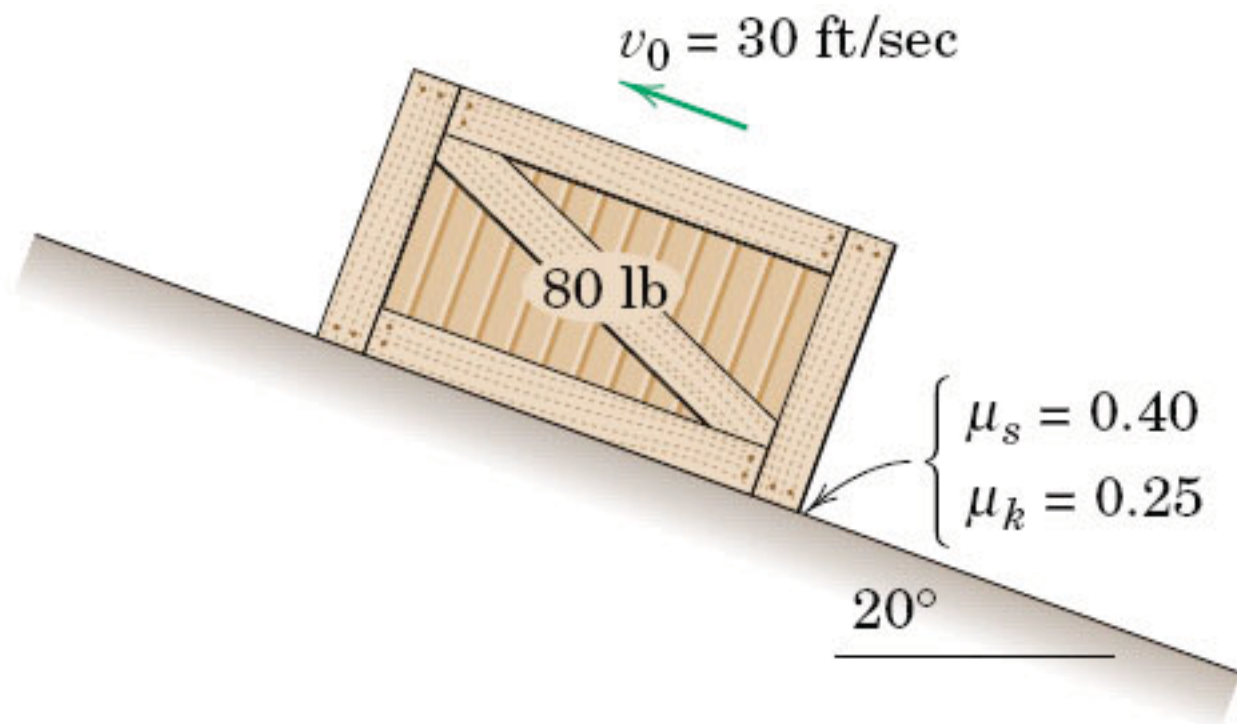
$$\sum \mathbf{F} = \sum F_x \mathbf{i} + \sum F_y \mathbf{j} + \sum F_z \mathbf{k}$$

$$|\sum \mathbf{F}| = \sqrt{(\sum F_x)^2 + (\sum F_y)^2 + (\sum F_z)^2}$$

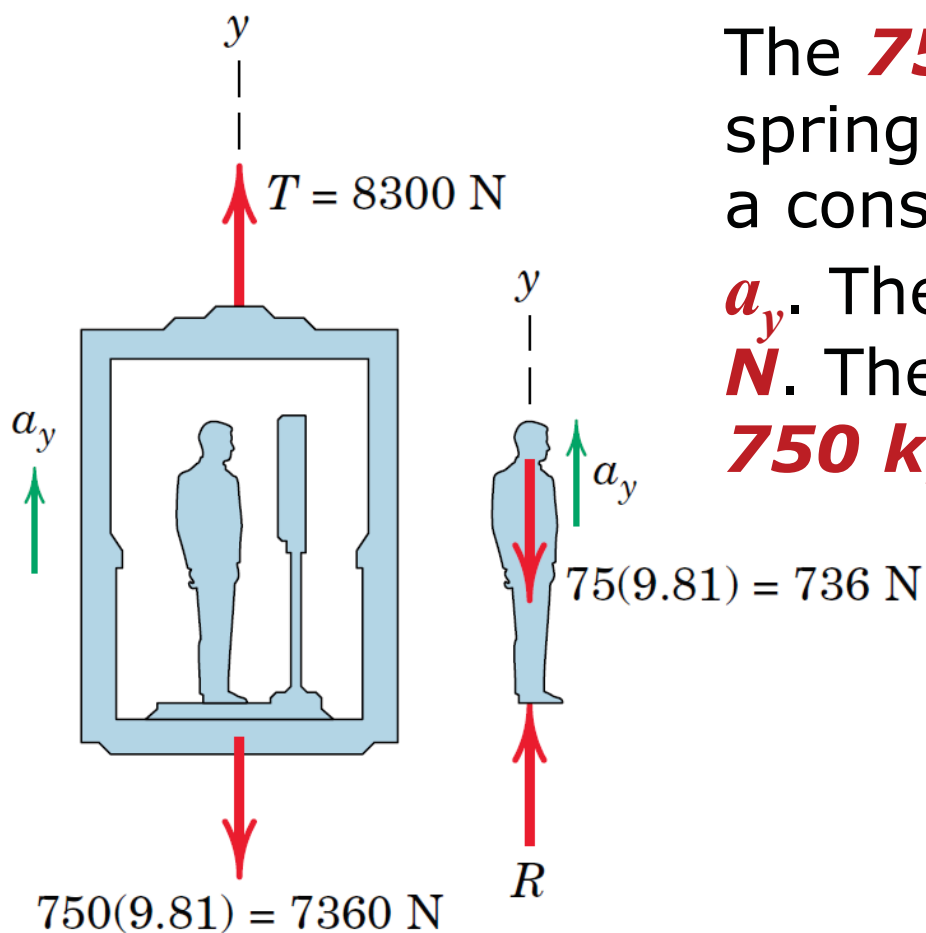
## Rectilinear Motion: Exercise

The **80-lb crate** has a **velocity** of **30 ft/s** up the incline.

Calculate the **time** required for the crate to come to **rest**.



## Rectilinear Motion: Another Exercise

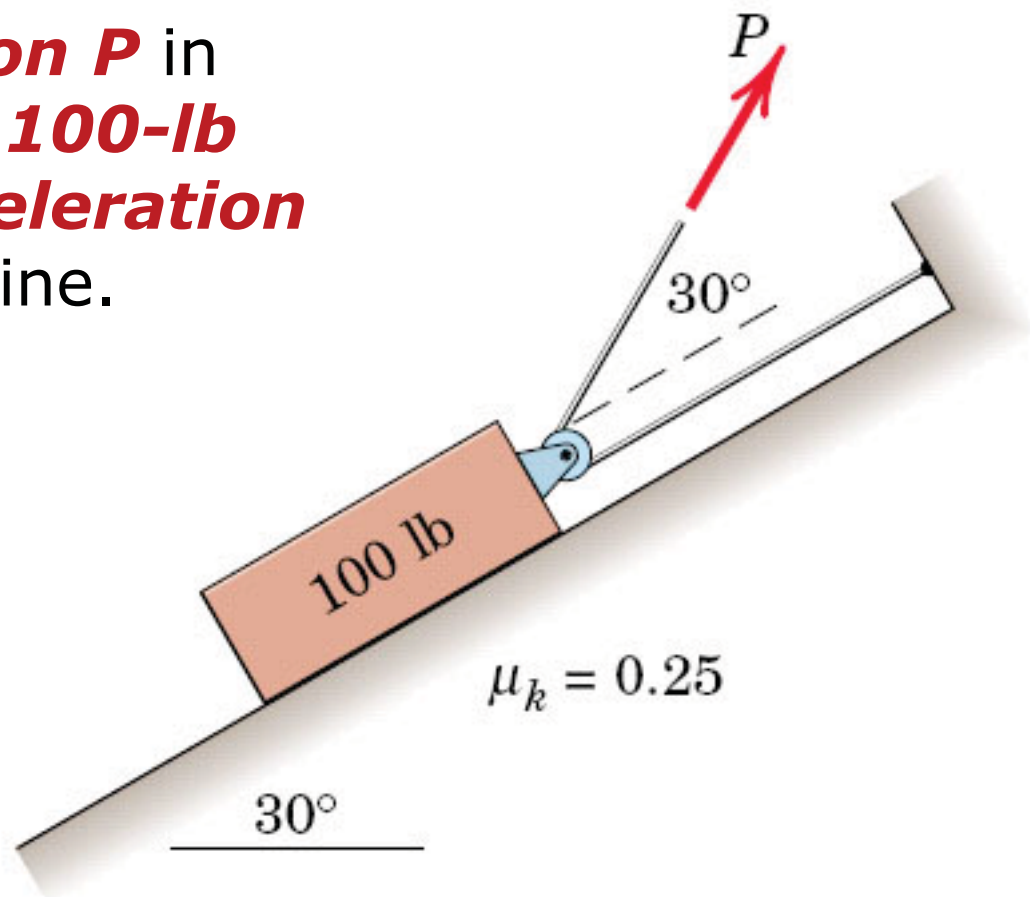


The **75-kg** man stands on a spring scale in an elevator with a constant upward **acceleration**  $a_y$ . The cable **tension**  $T$  is **8300 N**. The total system **mass** is **750 kg**.

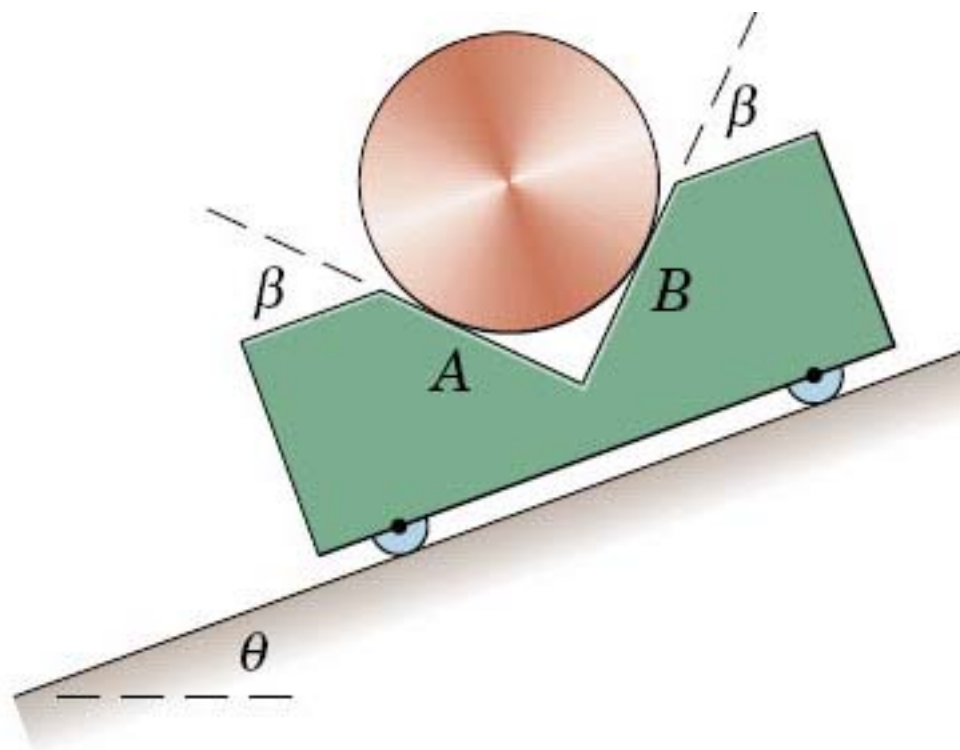
Find the **reading**  $R$  (in Newtons) of the scale.

## Rectilinear Motion: Yet Another Exercise

Determine the **tension  $P$**  in the cable to give the **100-lb** block a constant **acceleration** of  **$5 \text{ ft/s}^2$**  up the incline.



## Rectilinear Motion: One More Exercise



A cylinder rests in a supporting carriage where  $\beta = 45^\circ$  and  $\theta = 30^\circ$ .

Calculate the maximum **acceleration  $a$**  up the incline so that the cylinder does not lose contact with the carriage.

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## For Next Time...

- Continue Homework #7 due ***next Wednesday*** (10/17)
- Read Chapter 3, Sections 3.1 & 3.2